# Exploratory data analysis of extreme values using non-parametric kernel methods

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### Outline

- Motivation
- Kernel Density Estimators
- Simulation Study
- Real Data Application
- Conclusion

### Motivation

- Goal: Projection of extreme events, calculation of return levels
- e.g. Climate (rainfall, wind, temperature, ...)
- Numerous models in the literature
- Problem: Which one is the most appropriate?

## Motivating Example (1)

Perkins et al. (2013): AR4 models (28) to investigate changes in temperature extremes

Model evaluation based on 3 skills:

- 1. Means
- 2. PDFs
- 3. Tails: Observed histogram  $Z_o$  is surrogate of the true density. Tail index is

$$T = \sum_{i=1}^{n} W_i |Z_o^i - Z_m^i|$$

where  $W_i$  is the weight of bin i,  $Z_o$  and  $Z_m$  are the observed and modeled frequencies.

# Motivating Example (2)

### Drawbacks:

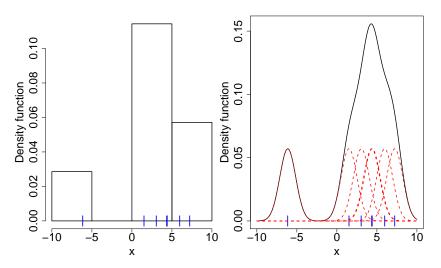
- Comparison of continuous models:
  - ▶ Discretization ⇒ distortion of the model
- Data driven choices: bin width, bin weights, ...
- Unsuitable for multivariate extremes

### Solution: Non-parametric Kernel Density Estimators (KDE)

- Continuous and robust (less arbitrary choices, can be applied to different datasets) 
   ⇒ Refinement of existing method
- Works with multi-variables ⇒ Multivariate extension

# **KDE** (1)

### How do they work?



# **KDE** (2)

What? A KDE is given by

$$\hat{f}_X(x;h) = \frac{1}{n} \sum_{i=1}^n K_h(x - X_i) = \frac{1}{nh} \sum_{i=1}^n K\left(\frac{x - X_i}{h}\right)$$

where K = kernel and h = bandwidth.

### Why?

- Not affected as much by the mass of the data
- Good overall properties (continuity, smoothness, fast cv)

Drawback: noise/bias at the boundary of the support

⇒ Transformation to focus on the tail and reduce bumps

### Framework for Tail Estimation

$$(\text{Random sample}) \\ X \sim f_X \\ \Downarrow \\ (\text{Tail sample}) \\ \boldsymbol{X}^{[u]} \equiv X|X>u, X^{[u]} \in (u,\infty) \\ \Downarrow \\ (\text{Monotonic transformation}) \\ \boldsymbol{Y} = t(X^{[u]}), \ \boldsymbol{Y} \sim f_Y \\ \Downarrow \\ f_{X^{[u]}}(x) = |t'(x)|f_Y(t(x)) \\ \Downarrow \\ \hat{f}_Y(y;h) = n^{-1} \sum_{i=1}^n K_h(y-Y_i) \\ \Downarrow \\ (\text{Tail density estimator}) \\ \hat{f}_{X^{[u]}}(x;h) = |t'(t^{-1}(y)|\hat{f}_Y(y;h)$$

### Main Result

**Definition 1** (Mean Integrated Square Error - MISE). For the density estimator  $\hat{f}_Y$ , the MISE is

MISE 
$$\hat{f}_Y(\cdot; h) = \mathbb{E} \int_{\mathbb{R}} [\hat{f}_Y(y; h) - f(y)]^2 dy.$$

**Theorem 1** (Minimal MISE of  $\hat{f}_{X[u]}$ ). Under suitable regularity conditions, as  $n \to \infty$ ,

$$\inf_{h>0} \operatorname{MISE} \hat{f}_{X^{[u]}}(\cdot; h) - \left\{ \inf_{h>0} \operatorname{MISE} \hat{f}_{Y}(\cdot; h) \right\} = O(n^{-4/5})$$

#### In other words:

- Bandwidth selection and estimation for transformed data Y retains same asymptotic optimality as original data  $X^{[u]}$
- Can use existing results/algorithms

# Simulation Study (1)

Targets (3): Fréchet, Gumbel and Generalized Pareto (GPD)

- 1. Generate 2000 replicates
- 2. Tail sample: u=95% quantile, target tail density  $f_{X^{[u]}}$
- 3. Transformation:  $t(x) = \log(x u)$
- 4. Fit: parametric models (3), histogram and kernel
- 5. Iterate 400 times
- 6. Comparisons:
  - 6.1  $L_2$  distance between target and fitted densities, e.g.  $\int_{u}^{\infty} [\hat{f}_{X^{[u]}}(x) f_{X^{[u]}}(x)]^2 dx$
  - 6.2  $T_h$  and  $T_k$ : histogram and Kernel based tail indices for  $u^* = 99\%$  quantile to avoid boundary bias at x = u affecting model selection, e.g.  $T = \int_{u^*}^{\infty} |\hat{f}_{X^{[u]}}(x) f_{X^{[u]}}(x)| \, dx$

# Simulation Study (2)

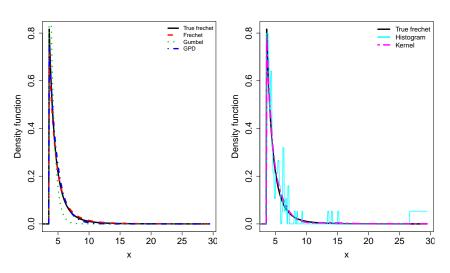


Figure: Parametric (left) and non-parametric (right) estimators of a Fréchet tail density.

# Simulation Study (3)

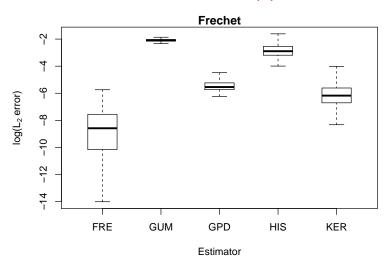


Figure: Boxplot of the  $L_2$  distances between estimated densities and target Fréchet density.

# Simulation Study (4)

		$T_h$			$T_k$	
Target	Fréchet	Gumbel	GDP	Fréchet	Gumbel	GDP
Fréchet	0.120	0.202	0.678	0.937	0	0.063
Gumbel	0.400	0.592	0.008	0.595	0.400	0.005
GPD	0.012	0.915	0.073	0.067	0.035	0.898

Table: Proportion of accepting a parametric model using histogram and kernel based tail indices.

**Remark**: True model is Gumbel:  $\bar{T}_h = 0.361$  whereas  $\bar{T}_k = 0.027$ .

# Real Data Application (1)

- Data: Daily max temperatures in Sydney for 1911-2005 (36890 obs).
- Comparison with physical models and histogram/KDEs
- Perkins et al. (2007): Histogram as surrogate for model densities
- Model selection:
  - $ightharpoonup T_h$ : CCMC.CESM, MPI.ESM.MR, CCMS.CMS
  - ► T<sub>k</sub>: MPI.ESM.MR, MIROC5, HadGEM2.CC
  - ► Same 5 worst models

## Real Data Application (2)

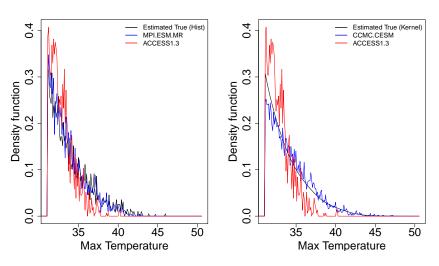


Figure: Best and worst models according to the histogram (left) and kernel (right) based tail indices.

### Conclusion

#### Results:

- Model selection method for extreme values
- More robust and continuous estimator of the tail density
- Efficiency proved for univariate simulated data
- Application to temperature data

### Work in progress:

- Extension of the simulations to the bivariate case
- Bivariate real data application (max and min temperatures)

# Many thanks for your attention!